Table of contents

- 1 Introduction
- 2 Discrete-Time Systems and the z-Transform
- 3 Sampling and Reconstruction
- 4 Open-Loop Discrete-Time Systems
- 5 Closed-Loop Systems
- 6 System Time-Response Characteristics
- 7 Stability Analysis Techniques
- 8 Digital Controller Design
- 9 Pole-Assignment Design and State Estimation
- 10 Linear Quadratic Optimal Control
- 11 Sampled-Data Transformation of Analog Filters
- 12 Digital Filter Structures
- 13 Microcomputer Implementation of Digital Filters
- 14 Finite-Wordlength Effects
- 15 Case Studies
- Appendices
- Index