

Table of Contents

- Control System Analysis
- Nonlinear Dynamics
- Basic Feedback Concept
- Frequency-domain analysis of relay feedback systems
- Linear Matrix Inequalities in Automatic Control
- Stability Analysis
- Motion Control Issues
- Control System Design
- PID Control
- The Nyquist Criterion
- The Root Locus Method
- A New Methodology for Chatter Stability Analysis in Simultaneous Machining
- Internal Mode Control
- Dynamic Matrix Control
- Variable Structure Control Technique
- Digital Control
- Phase-Lock-Loop Based Control
- Optimal Control
- Time-Delay Systems
- Terminal Sliding Mode Control of Permanent Magnet Synchronous Motors
- Predictive Repetitive Control with Constraints
- Backstepping Control
- Sensors
- Observers in Dynamic Engineering Systems
- Soft Computing Methodologies in SMC
- Estimation, Observation, and Identification
- Adaptive Estimation
- Modeling and Control
- Modeling for System Control
- A State-Space Approach to Simulating Dynamic Systems in SPICE
- Iterative Learning Control for Torque Ripple Minimization of Switched Reluctance Motor Drive
- Precise Position Control of Piezo Actuator
- Disturbance Observation-Cancellation Technique
- Ultrasonic Sensors
- Observation and Identification via HOSM
- Intelligent Mechatronics and Robotics
- Hardware-in-the-loop simulations
- Mechatronic and Robotics
- Actuators in Robotics and Automation Systems
- Robot Qualities
- Robot Vision
- Robot Path Planning
- Mobile Robots

- Introduction to Mechatronics Systems