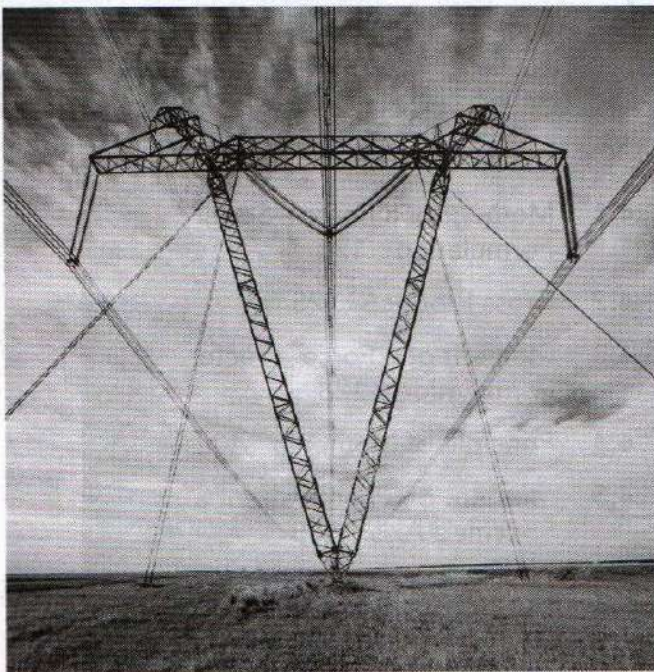


# CONTENTS



## 1 General Principles 3

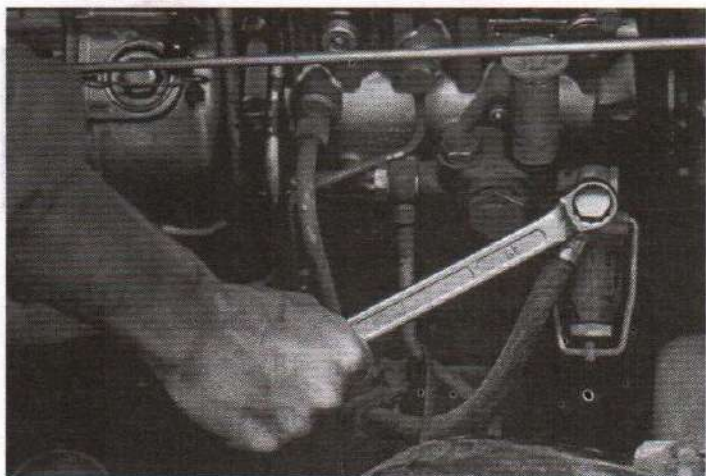
Chapter Objectives 3

- 1.1 Mechanics 3
- 1.2 Fundamental Concepts 4
- 1.3 The International System of Units 7
- 1.4 Numerical Calculations 10
- 1.5 General Procedure for Analysis 12

## 2 Force Vectors 17

Chapter Objectives 17

- 2.1 Scalars and Vectors 17
- 2.2 Vector Operations 18
- 2.3 Vector Addition of Forces 20
- 2.4 Addition of a System of Coplanar Forces 33
- 2.5 Cartesian Vectors 44
- 2.6 Addition of Cartesian Vectors 47
- 2.7 Position Vectors 56
- 2.8 Force Vector Directed Along a Line 59
- 2.9 Dot Product 69



### 3 Equilibrium of a Particle 87

Chapter Objectives 87

- 3.1 Condition for the Equilibrium of a Particle 87
- 3.2 The Free-Body Diagram 88
- 3.3 Coplanar Force Systems 91
- 3.4 Three-Dimensional Force Systems 106

### 4 Force System Resultants 121

Chapter Objectives 121

- 4.1 Moment of a Force—Scalar Formulation 121
- 4.2 Cross Product 125
- 4.3 Moment of a Force—Vector Formulation 128
- 4.4 Principle of Moments 132
- 4.5 Moment of a Force about a Specified Axis 145
- 4.6 Moment of a Couple 154
- 4.7 Simplification of a Force and Couple System 166
- 4.8 Further Simplification of a Force and Couple System 177
- 4.9 Reduction of a Simple Distributed Loading 190



## 5 Equilibrium of a Rigid Body 207

Chapter Objectives 207

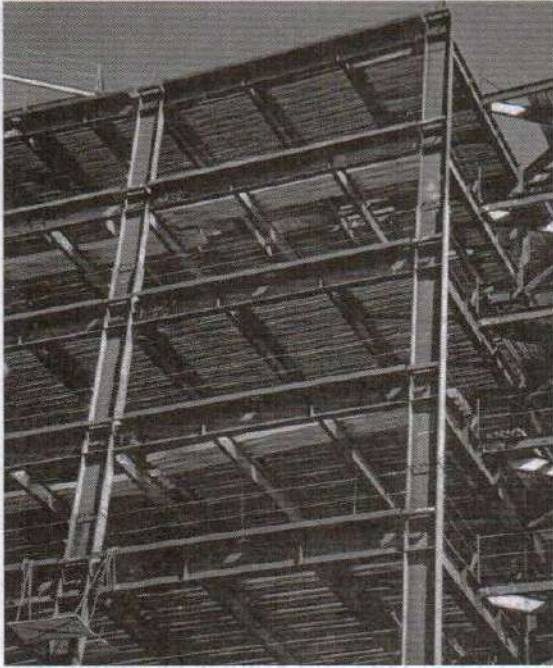
- 5.1 Conditions for Rigid-Body Equilibrium 207
- 5.2 Free-Body Diagrams 209
- 5.3 Equations of Equilibrium 220
- 5.4 Two- and Three-Force Members 230
- 5.5 Free-Body Diagrams 245
- 5.6 Equations of Equilibrium 250
- 5.7 Constraints and Statical Determinacy 251



## 6 Structural Analysis 273

Chapter Objectives 273

- 6.1 Simple Trusses 273
- 6.2 The Method of Joints 276
- 6.3 Zero-Force Members 282
- 6.4 The Method of Sections 291
- 6.5 Space Trusses 301
- 6.6 Frames and Machines 305

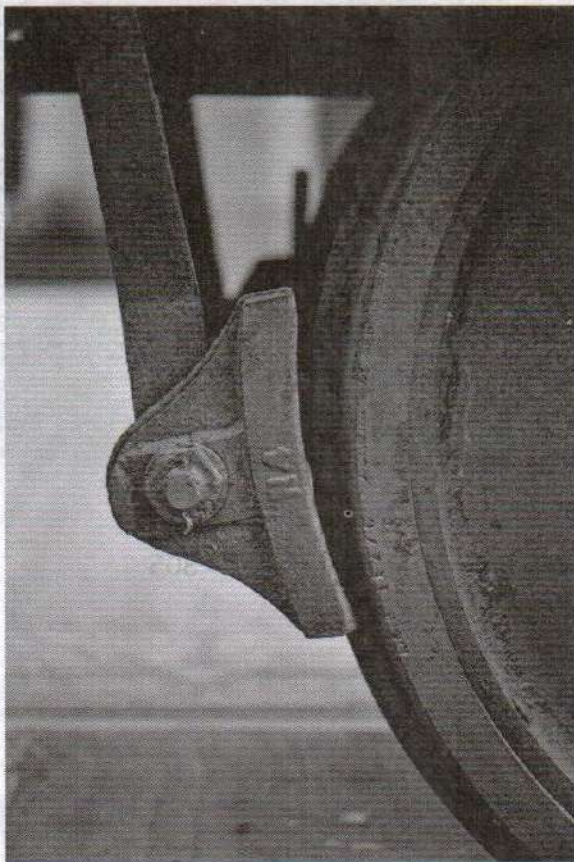


## 7

### Internal Forces 343

Chapter Objectives 343

- 7.1 Internal Loadings Developed in Structural Members 343
- 7.2 Shear and Moment Equations and Diagrams 361
- 7.3 Relations between Distributed Load, Shear, and Moment 370
- 7.4 Cables 381

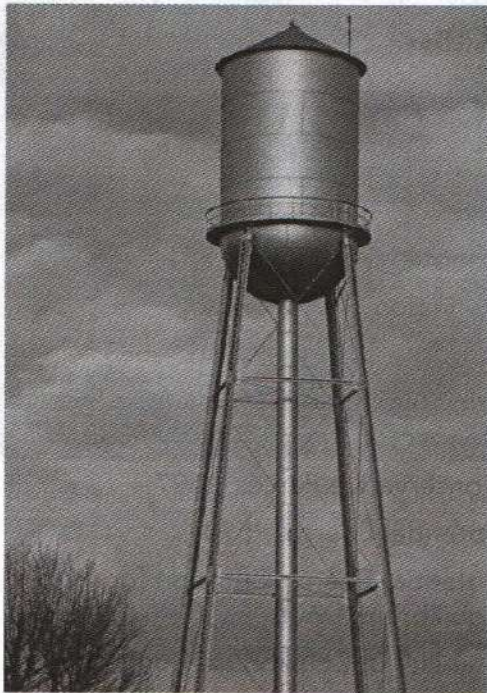


## 8

### Friction 401

Chapter Objectives 401

- 8.1 Characteristics of Dry Friction 401
- 8.2 Problems Involving Dry Friction 406
- 8.3 Wedges 430
- 8.4 Frictional Forces on Screws 432
- 8.5 Frictional Forces on Flat Belts 439
- 8.6 Frictional Forces on Collar Bearings, Pivot Bearings, and Disks 447
- 8.7 Frictional Forces on Journal Bearings 450
- 8.8 Rolling Resistance 452



## 9 Center of Gravity and Centroid 465

Chapter Objectives 465

- 9.1 Center of Gravity, Center of Mass, and the Centroid of a Body 465
- 9.2 Composite Bodies 488
- 9.3 Theorems of Pappus and Guldinus 502
- 9.4 Resultant of a General Distributed Loading 511
- 9.5 Fluid Pressure 512

## 10 Moments of Inertia 529

Chapter Objectives 529

- 10.1 Definition of Moments of Inertia for Areas 529
- 10.2 Parallel-Axis Theorem for an Area 530
- 10.3 Radius of Gyration of an Area 531
- 10.4 Moments of Inertia for Composite Areas 540
- 10.5 Product of Inertia for an Area 548
- 10.6 Moments of Inertia for an Area about Inclined Axes 552
- 10.7 Mohr's Circle for Moments of Inertia 555
- 10.8 Mass Moment of Inertia 563





## 11 Virtual Work 581

- Chapter Objectives 581
- 11.1 Definition of Work 581
- 11.2 Principle of Virtual Work 583
- 11.3 Principle of Virtual Work for a System of Connected Rigid Bodies 585
- 11.4 Conservative Forces 597
- 11.5 Potential Energy 598
- 11.6 Potential-Energy Criterion for Equilibrium 600
- 11.7 Stability of Equilibrium Configuration 601

## 12 Kinematics of a Particle 617

- Chapter Objectives 617
- 12.1 Introduction 617
- 12.2 Rectilinear Kinematics: Continuous Motion 619
- 12.3 Rectilinear Kinematics: Erratic Motion 634
- 12.4 General Curvilinear Motion 648
- 12.5 Curvilinear Motion: Rectangular Components 650
- 12.6 Motion of a Projectile 655
- 12.7 Curvilinear Motion: Normal and Tangential Components 670
- 12.8 Curvilinear Motion: Cylindrical Components 685
- 12.9 Absolute Dependent Motion Analysis of Two Particles 699
- 12.10 Relative-Motion of Two Particles Using Translating Axes 705



## 13 Kinetics of a Particle: Force and Acceleration 727

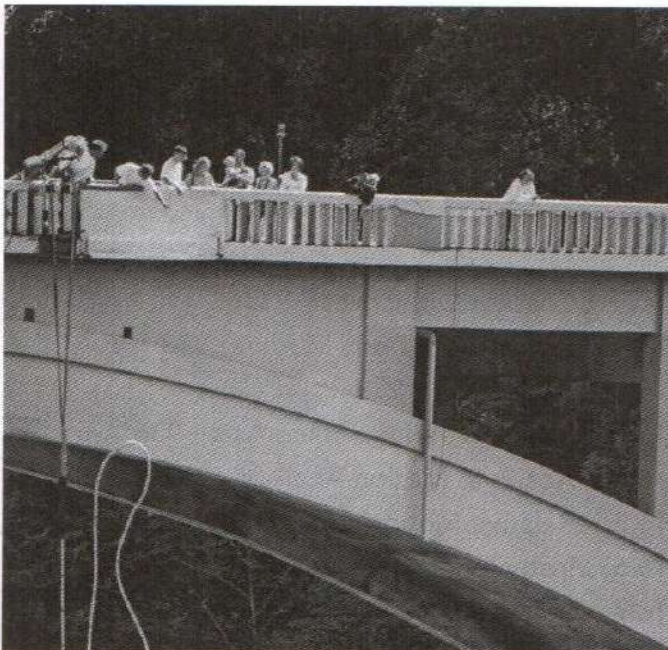
Chapter Objectives 727

- 13.1 Newton's Second Law of Motion 727
- 13.2 The Equation of Motion 730
- 13.3 Equation of Motion for a System of Particles 732
- 13.4 Equations of Motion: Rectangular Coordinates 734
- 13.5 Equations of Motion: Normal and Tangential Coordinates 752
- 13.6 Equations of Motion: Cylindrical Coordinates 766
- \*13.7 Central-Force Motion and Space Mechanics 778

## 14 Kinetics of a Particle: Work and Energy 793

Chapter Objectives 793

- 14.1 The Work of a Force 793
- 14.2 Principle of Work and Energy 798
- 14.3 Principle of Work and Energy for a System of Particles 800
- 14.4 Power and Efficiency 818
- 14.5 Conservative Forces and Potential Energy 827
- 14.6 Conservation of Energy 831



13.8 Relative Motion Analysis Using Rotating Axes 1003



## 15 Kinetics of a Particle: Impulse and Momentum 851

- Chapter Objectives 851
- 15.1 Principle of Linear Impulse and Momentum 851
- 15.2 Principle of Linear Impulse and Momentum for a System of Particles 854
- 15.3 Conservation of Linear Momentum for a System of Particles 868
- 15.4 Impact 880
- 15.5 Angular Momentum 894
- 15.6 Relation Between Moment of a Force and Angular Momentum 895
- 15.7 Principle of Angular Impulse and Momentum 898
- 15.8 Steady Flow of a Fluid Stream 909
- \*15.9 Propulsion with Variable Mass 914

## 16 Planar Kinematics of a Rigid Body 933

- Chapter Objectives 933
- 16.1 Planar Rigid-Body Motion 933
- 16.2 Translation 935
- 16.3 Rotation about a Fixed Axis 936
- 16.4 Absolute Motion Analysis 952
- 16.5 Relative-Motion Analysis: Velocity 960
- 16.6 Instantaneous Center of Zero Velocity 974
- 16.7 Relative-Motion Analysis: Acceleration 987
- 16.8 Relative-Motion Analysis Using Rotating Axes 1003





## 17 Planar Kinetics of a Rigid Body: Force and Acceleration 1023

Chapter Objectives 1023

- 17.1 Mass Moment of Inertia 1023
- 17.2 Planar Kinetic Equations of Motion 1037
- 17.3 Equations of Motion: Translation 1040
- 17.4 Equations of Motion: Rotation about a Fixed Axis 1055
- 17.5 Equations of Motion: General Plane Motion 1070



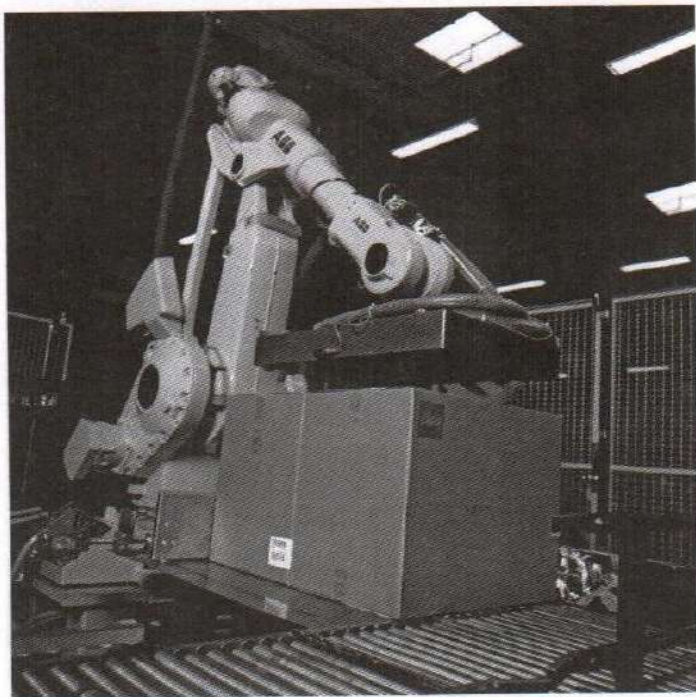
## 18 Planar Kinetics of a Rigid Body: Work and Energy 1087

Chapter Objectives 1087

- 18.1 Kinetic Energy 1087
- 18.2 The Work of a Force 1090
- 18.3 The Work of a Couple Moment 1092
- 18.4 Principle of Work and Energy 1094
- 18.5 Conservation of Energy 1110



17.4 Equations of Motion: Rotation about a Fixed Axis 1052  
 17.5 Equations of Motion: General Plane Motion 1070



18.3 The Work of a Couple Moment 1092  
 18.4 Principle of Work and Energy 1094  
 18.5 Conservation of Energy 1110

## 19

### Planar Kinetics of a Rigid Body: Impulse and Momentum 1131

Chapter Objectives 1131

- 19.1 Linear and Angular Momentum 1131
- 19.2 Principle of Impulse and Momentum 1137
- 19.3 Conservation of Momentum 1154
- \*19.4 Eccentric Impact 1158

## 20

### Three-Dimensional Kinematics of a Rigid Body (Web Chapter)

Chapter Objectives

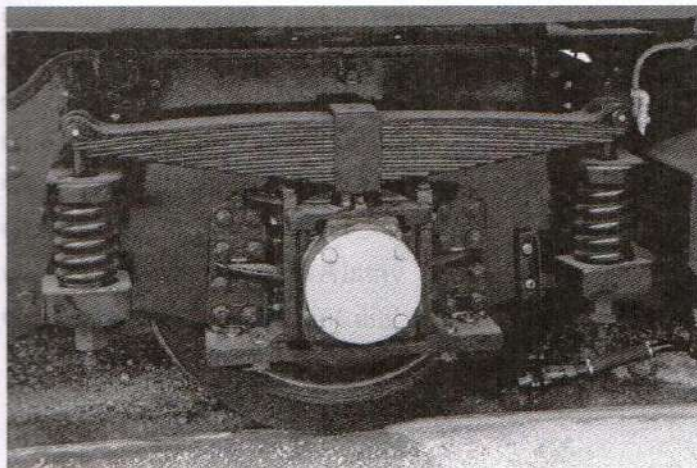
- 20.1 Rotation about a Fixed Point
- \*20.2 The Time Derivative of a Vector Measured from Either a Fixed or Translating-Rotating System
- 20.3 General Motion
- \*20.4 Relative-Motion Analysis Using Translating and Rotating Axes



## 21 Three-Dimensional Kinetics of a Rigid Body (Web Chapter)

### Chapter Objectives

- \*21.1 Moments and Products of Inertia
- 21.2 Angular Momentum
- 21.3 Kinetic Energy
- \*21.4 Equations of Motion
- \*21.5 Gyroscopic Motion
- 21.6 Torque-Free Motion



## 22 Vibrations (Web Chapter)

### Chapter Objectives

- \*22.1 Undamped Free Vibration
- \*22.2 Energy Methods
- \*22.3 Undamped Forced Vibration
- \*22.4 Viscous Damped Free Vibration
- \*22.5 Viscous Damped Forced Vibration
- \*22.6 Electrical Circuit Analogs

**Appendix**

- A. Mathematical Review and Expressions 1174
- B. Vector Analysis 1178
- C. The Chain Rule 1183

**Fundamental Problems  
Partial Solutions and  
Answers 1186****Preliminary  
Problems 1224****Review Problem  
Solutions 1244****Answers to Selected  
Problems 1265****Index 1287**